

**IN THE SPECIFICATION:**

Please amend the section heading at line 4, page 1, as follows:

**[[Field of the Invention]] BACKGROUND OF THE INVENTION**

Please delete the section heading at line 9, page 1, as follows:

**[[BACKGROUND FOR THE INVENTION]]**

Please amend the section heading at line 5, page 3, as follows:

**[[BRIEF SUMMARY OF THE INVENTION]] BRIEF SUMMARY OF THE INVENTION**

Please amend the section heading at line 24, page 4, as follows:

**[[DESCRIPTION OF THE DRAWINGS]] BRIEF DESCRIPTION OF THE DRAWINGS**

Please amend the section heading at line 21, page 6, as follows:

**[[DESCRIPTION OF THE PREFERRED EMBODIMENTS OF THE INVENTION]] DETAILED DESCRIPTION OF THE INVENTION**

Please amend the paragraph at line 7, page 9 as follows:

As illustrated in Figure 5, a loader [[51]] 50 may be of a conventional design and may be adjacent to the die carrier 24 or positioned thereon. The loader/unloader [[51]] 50 includes a pair of air cylinders 52 and 54 for positioning a load blank 53 in front of a die 56. The first cylinder 52 moves a load carrier 55 horizontally from a first position into alignment with the die 56. The second air cylinder 54 then positions the load blank 53 in front of the die where it is delivered into the die 56 by one of the punches. The carrier 55 is then returned to a first position in a conventional manner.

Please amend the paragraph at line 24, page 9, as follows:

The multi access controller 104 which is operatively connected to a hydraulic servo [[108]] 105 to control movement of a pair of parallel die platen pistons in die platen cylinders 110 and 112. A second Tempasonic position feedback output device 114 is operably connected to the multi access controller 104 to convey feedback data to the controller 104.

Please amend the paragraph at line 22, page 10 as

follows:

An improved conveyor or loader/unloader 200 in accordance with a preferred embodiment of the invention will now be described in connection with Figures 7-15. As illustrated therein, a loader/unloader 200 is adapted to receive a work piece 202 from a supply source (not shown) and to convey or transport the work piece 202 to a loading/unloading position 204 adjacent to a die 206 and between a punch 208 and the die 206. The loader/unloader 200 includes a pivot assembly 210 and a J-shaped moveable robot arm 212 with one end 214 attached to the pivot assembly 210 for movement about a central axis 223 about which the pivot assembly rotates.